# Sunoh Lee

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### **Research Interests**

#### **Computer Vision**

Open-World Perception, Open-Vocabulary Interaction, Representation Learning

### **Education**

## Gwangju Institute of Science and Technology (GIST)

Mar 2018 – Feb 2022

Bachelor of Science in Electrical Engineering and Computer Science Minor in Economics

GPA: 4.2/4.5 (rank: 1/121)

### **Hansung Science High School**

Mar 2015 - Feb 2018

#### **Publications**

### • Open-World Object Detection with Instance Representation Learning [paper]

Sunoh Lee\*, Minsik Jeon\*, Jihong Min, Junwon Seo
Submitted to IEEE International Conference on Robotics and Automation (ICRA), 2025
Accepted to IROS Workshop on Label Efficient Learning Paradigms for Autonomy at Scale, 2024

### **Work Experience**

### Republic of Korea Army (ROKA)

Jun 2022 - Present

First Lieutenant

Daejeon, Republic of Korea

Selected as one of the 25 officers in Korea dedicated to science and technology research for national defense.
 Assigned to ADD for the development of defense technology.

#### **Agency for Defense Development (ADD)**

Jun 2022 - Present

Deep Learning Researcher

Daejeon, Republic of Korea

### Project: Multi Robot Cooperative Autonomous Driving

- Developed a method to merge detection results, enabling multiple Unmanned Ground Vehicles (UGVs) to cooperate effectively while in motion, based on ROS2.

#### Project: Unmanned Reconnaissance Vehicles Development

 Developed a method to filter moving objects from LiDAR points using the Iterative Closest Point (ICP) algorithm, enabling robust path planning.

#### Project: Autonomous Tunnel Exploitation

- Developed an **unseen object detection** method for autonomous robotic exploration in subterranean environments using an **IP-camera and ROS2**.
- Extracted **generalizable latent features** of previously unlearnable objects, enabling the system to recognize **similarities between objects** and detect hazardous materials.

<sup>\*</sup> indicates equal contribution.

### • Project: Deformable Object Recognition Technology

- Constructed a dataset to enable the detection of deformable objects, such as animals, which may appear in **specific environments** like off-road terrain, rather than common objects like humans or vehicles.
- Developed a voxel-based 3D object detection method using LiDAR to identify deformable objects.

### **Computer Vision Lab (GIST)**

Mar 2021 – Dec 2021

Researcher Intern

Gwangju, Republic of Korea

Advisor: Prof. Jonghyun Choi

### • Project: Image Dataset occluded by various type of wires

- Built an image dataset of objects occluded by various types of wires and validated it through object classification and segmentation.
- Conducted performance analysis on object recognition under wire occlusions using various augmentations and data preprocessing techniques.

### **Teaching Experience**

Tutor, Linear Algebra, Gwangju Institute of Science and Technology

#### **Selected Awards & Honors**

• 2nd Place - Forest Public • Big Data Start-up Competition

Sep 2022

Won second place in a start-up competition organized by Korea Forest Service

IDEA: Customized hiking trail recommendation service

National Excellence Scholarship for Science and Engineering

Mar 2020 – Feb 2022

• National Scholarship for Undergraduate Study

Mar 2018 – Feb 2020

#### Skills

**Programming Languages**: python, C/C++, MATLAB

Technologies: Pytorch, Docker, Git, OpenCV, ROS2, Ubuntu

Languages: Korean (Native), English (TOEIC: Will be uploaded)

### **Extracurricular Activities**

#### **Volunteer Activities**

World Friends ICT Volunteers Program in Moldova

Jun 2019 - Jul 2019

Provided programming and Korean language education, along with cultural exchange activities.

• Happy Move Global Youth Volunteer Program in India

Jul 2018

Developed appropriate desk technology for small spaces, participated in school facility maintenance, and engaged in cultural exchange initiatives.

The dormitory council

Sep 2018 – Feb 2020

Planned and organized various events and welfare programs